

MALAYSIAN JOURNAL OF ANALYTICAL SCIENCES

Published by The Malaysian Analytical Sciences Society

ISSN 1394 - 2506

AIR QUALITY PATTERN ASSESSMENT IN MALAYSIA USING MULTIVARIATE TECHNIQUES

(Penilaian Corak Kualiti Udara di Malaysia Menggunakan Teknik Multivariat)

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Received: 14 April 2015; Accepted: 9 July 2015

Abstract

This study aims to investigate the spatial characteristics in the pattern of air quality monitoring sites, identify the most discriminating parameters contributing to air pollution, and predict the level of air pollution index (API) in Malaysia using multivariate techniques. Five parameters observed for five years (2000-2004) were used. Hierarchical agglomerative cluster analysis classified the five air quality monitoring sites into two independent groups based on the characteristics of activities in the monitoring stations. Discriminate analysis for standard, backward stepwise and forward stepwise mode gave a correct assignation of more than 87% in the confusion matrix. This result indicates that only three parameters (PM₁₀, SO₂ and NO₂) with a p<0.0001 discriminate best in polluting the air. The major possible sources of air pollution were identified using principal component analysis that account for more than 58% and 60% in the total variance. Based on the findings, anthropogenic activities (vehicular emission, industrial activities, construction sites, bush burning) have a strong influence in the source of air pollution. Furthermore, artificial neural network (ANN) was used to predict the level of air pollution index at R² = 0.8493 and RMSE = 5.9184. This indicates that ANN can predict more than 84% of the API.

Keywords: multivariate techniques, principal component analysis, artificial neural network, air pollution index

Abstrak

Kajian ini adalah bertujuan untuk menyiasat ciri-ciri *spatial* dalam pemantauan corak kualiti udara, mengenal pasti parameter yang menjadi penyumbang kepada pencemaran udara, dan meramalkan tahap indeks pencemaran udara (IPU) di Malaysia menggunakan teknik multivariat. Lima parameter udara bagi lima tahun (2000-2004) telah digunakan. Hirarki algorithma analisa kelompok telah mengkelaskan lima tapak pemantauan kualiti udara kepada dua kumpulan berdasarkan ciri-ciri aktiviti di stesen pemantauan. Analisis pembezalayan bagi kaedah *standard*, langkah demi langkah ke belakang dan langkah demi langkah ke hadapan memberikan peratusan yang dibenar lebih daripada 87% dalam matriks kekeliruan. Keputusan ini menunjukkan bahawa hanya tiga parameter (PM₁₀, SO₂ dan NO₂) dengan *p*<0,0001 memberikan pembezalayan yang baik dalam pencemaran di udara. Sumber utama kemungkinan pencemaran udara telah dikenal pasti menggunakan analisis komponen utama yang menyumbang lebih daripada 58% dan 60% dalam jumlah varians. Berdasarkan hasil kajian, aktiviti antropogenik (pelepasan kenderaan, aktiviti perindustrian, tapak pembinaan, pembakaran belukar) mempunyai pengaruh yang kuat dalam sumber pencemaran udara. Tambahan pula, rangkaian neural buatan (RNB) telah digunakan untuk meramal tahap indeks pencemaran udara dengan nilai R² = 0.8493 dan RMSE = 5.9184. Ini menunjukkan bahawa RNB boleh meramalkan IPU lebih daripada 84%.

Kata kunci: teknik multivariate, analisis komponen utama, rangkaian neural buatan, indeks pencemaran udara

Introduction

Air is the most precious natural resources that sustain the existence of man, animals, plants as well as the general ecosystem regulation. It is a mixture of gasses which serves as a spacesuit of the biosphere and held by the force of gravity [1,2]. Air helps to retain heat that warms the earth surface, reduces temperature extremes between day and night as well as absolve ultraviolet solar radiation [3]. The quality of air is determined by measuring the concentration of gaseous pollutants and sizes or number of particulate matter emitted from natural or anthropogenic sources [4]. Air is polluted when particulate toxic elements and gasses released into the atmosphere build up in concentration sufficiently high to cause damage [5,6].

Atmospheric air pollution has adverse effect on the environment and health status of a given population. This is because air is polluted from various sources and its complexity is largely dependent on the meteorological characteristics, topography and the nature of the pollutants been emitted [7]. Rapid advancement in the level of industrial activities and population concentration within the second half of the twentieth century poses a serious threat to atmospheric air quality and well-being [8]. Furthermore, many accidental discharge of air pollutants results in acute exposure and potential risk on human health [9].

Despite the effort put in place by both government and stakeholders to monitor and control air pollution level, its negative and hazardous impact is enormous [10]. However, an estimate of the regional variability of air pollution can be best understood taking into account the location of monitoring sites within a study area [11]. Atmospheric air pollutants limits the amount of oxygen fed to the foetus through the mother when inhaled, thereby retarding the anthropometric development of the child by reducing its head circumference [12]. It can also cause environmental degradation (global warmining), lung cancer, asthma, cardiovascular and respiratory diseases [13,14].

API is used to identify and classify the ambient air quality in Malaysia base on the possible health implications to the public [15]. It is a non-dimensional number calculated according to the urban daily average concentration of pollutants [16,17]. API in Malaysia is calculated based on the sub-index using five air pollution parameters (PM_{10} , SO_2 , NO_2 , CO_2 and O_3). The highest sub-index value of the individual pollutants is used as the API value for a specific time period [16,18,19]. This is based on the Recommended Malaysia Ambient Air Quality Guideline (RMAQG) issued by the Department of Environment (DOE) since 1989 as; good, moderate, unhealthy, very unhealthy and hazardous. Although, it conform to international standard as provided by United State Environmental Protection Agency [19].

Atmospheric air quality monitoring involves observation of large complex data sets from stations that require the integration of modern and robust statistical techniques for simplification, avoid misinterpretation and to show spatial variation [20,21,22]. Several research has shown that the level of air pollution in Malaysia fall within the range of good and moderate but still show a slight fluctuation in trend from 2008 to 2011 [17]. In 2008, the status of good air quality fall around 59%, 55.6% in 2009, 63% in 2010 and 55% in 2011 [17].

The objectives of this study is to determine the spatial characteristics in the air quality monitoring sites, identify the sources of pollution and the most discriminating parameters contributing to the air pollution, and predict the level of air pollution index using artificial neural network.

Materials and Methods

Study Area

Five air quality monitoring sites were selected to give a general representation of the air quality status in Malaysia. These five monitoring stations are under the supervision and control by a private company (Alam Sakitar Malaysia Sdn. Bhd (ASMA) on behalf of Department of Environment Malaysia (DOE). The monitoring sites comprises of Pasir Gudang, Johor (ST01) located in the southern Peninsular Malaysia; Kemaman, Terengganu (ST02) located in the eastern Peninsular Malaysia; Perai, Pulau Pinang (ST03) in the Northern Peninsular Malaysia. Sibu Sarawak (ST04) and Tawu Sabah (ST05) are situated in the eastern Malaysia. Furthermore, the location of the study area base on their latitude and longitude are shown in Table 1 and Figure 1.

Site ID	Location	Latitude	Longitude
ST01	Pasir Gudang, Johor	N01° 28.225	E103° 53.637
ST02	Kemaman, Terengganu	N04° 16.260	E103° 25.826
ST03	Seberang, Perai, Pulau Pinang	N05° 23.890	E100° 24.194
ST04	Sibu, Sarawak	N02° 18.856	E111° 49.906
ST05	Tawau, Sabah	E117°56.166	N04 ° 15.016

Table 1. Location of study area based on latitude and longitude



Figure 1. Location of air quality monitoring stations

Data Treatment

Secondary data comprising of five air monitored pollutants were sourced from DOE in the form of hourly reading from 2000-2004. These hourly observations were converted to daily average reading in order to carry out a precise and accurate statistical analysis. A total of 27405 data sets (5481 observations \times 5 parameters) were used for the analysis. Furthermore, the nearest neighbour method was applied using XLSTAT add-in software to estimate missing values [16,23]. Nearest neighbor is used to predict unknown values using the known values at neighbouring locations where sample points lack [24]. The missing data recorded is 3% of the original data sets [23]. Suggested that nearest neighbor method can provide a simple scheme, where the endpoint of the gaps is used as estimates for all missing values. This equation was shown in equation 1 below:

$$y = y_1 \text{ if } x \le x_1 + [(x_2 - x_1)/2]$$

$$y = y_1 \text{ if } x \ge x_1 + [(x_2 - x_1)/2]$$
(1)

where y represents the interpolate, x is the time point of the interpolate, y_1 and x_1 are the coordinates of the starting point of the gap and y_2 and x_2 are the end points of the gaps.

Hierarchical Agglomerative Cluster Analysis (HACA)

HACA is an unsupervised statistical method used to spatially classify observations into group or clusters base on their similarities or differences [22,25,26]. This spatial classification of air quality monitoring station can be illustrated using a dendrogram that measures the degree of risk homogeneity through Ward's method and Euclidean distance measurement [27]. Euclidean distance is based on a single linkage which denotes the quotient between the

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linkage distance divided by the maximal distance [(Dlink/Dmax)], by multiplying the quotient by 100 in order to standardize the linkage distance represented by the y-axis [28,29,30].

Discriminate Analysis (DA)

DA is usually applied in order to identify the variables that best discriminate between groups developed by HACA and helps to construct new discriminant functions (DFs) for each group in order to evaluate the spatial variation in atmospheric air quality [21,31].

DFs are calculated using Equation 2:

$$F(G_i) = K_i + \sum_{i=1}^{n} w_{ii} P_{ij}$$
 (2)

where i = the number of group G; k_j = constant inherent to each group; n = the number of parameters used to classify a set of data into a given group; w_j = the weight coefficient assigned by discriminant function analysis (DFA) to a given parameter P_i .

In this study, DA is applied on the raw data for spatial analysis in the two clusters developed by HACA using standard mode, backward stepwise mode and forward stepwise mode to determine whether the group differ with regards to the mean of the variable and to use that variable to predict group membership. To achieve this, cluster 1 and 2 were selected as dependent variable, while the five monitored parameters represent the independent variables. Using the forward stepwise mode, variables were included step by step from the most significant until no significant changes are observed, while in the backward stepwise mode, variables were removed step by step beginning from the less significant variable until no significant changes were observed [21].

Principal Component Analysis

PCA is the most used pattern recognition technique for analysing large and complex data sets [22]. It is used to extract the most significant parameters by eliminating the less significant parameters with minimal loss of the original variables [28,29,30]. The equation is expressed as equation 3 below:

$$Z_{ij} = a_{i1}x_{1j} + a_{i2}x_{2j} + a_{i3}x_{3j} + \dots + a_{im}x_{mj}$$
(3)

where z is the component score, a is the component loading, x is the measured value of variables, i is the component number, j is the sample number and m is the total number of variables.

Although, the principal components (PCs) generated by PCA are sometimes not readily available for interpretation, therefore, it is advisable to rotate it by varimax rotation with eigenvalues greater than 1 [21]. The varimax rotation is considered significant in order to obtain new groups of variables called varimax factors (VFs) [32,33]. This will help identify the different possible sources of pollution [18,24].

Furthermore, the number of varimax factors(VFs) obtained by varimax rotations is usually equal to the number of variables in accordance with the common features which can include unobservable, hypothetical and latent variables [34,35]. In addition, the VFs coefficient with a correlation from 0.75 are considered as strong significant factor loading, those that range from 0.50 - 0.74 are moderate, while 0.30 - 0.49 are classified as weak significant factor loading [36]. The equation is expressed as equation 4 below:

$$Z_{ij} = af_1 x_{1i} + a_{f2} x_{2i} + \dots + a_{fm} f_{mi} + e_{fi}$$
(4)

where Z is the measured value of a variables, a is the factor loading, f is the factor score, e is the residual term accounting for errors or other sources variation, i is the sample number, j is the variable number and m is the total number of factors.

Artificial Neural Network (ANN)

ANN is a distributed information processing system and powerful general purpose software composed of many simple computational elements integrating across weighted connections [37]. It is a very sophisticated model used for forecasting the concentration of pollutants and to estimating the level of air pollution index [38]. In this study, a multilayer perceptron feed-forward artificial neural network (MLP-FF-ANN) was applied in order to predict the level of air pollution index.

The network structure is designed to consist of multiple neurons organized in layers that enable information to flow via an input system (independent variable). From the input layer signal is passed to the hidden layer via a system of weighted connection where the actual processing is done and finally reached the output layer (dependent variable) [39]. The network is trained severally by adjusting the weight value in order to minimize error and optimize the number of hidden nodes in each layer [40]. To achieve this, a Backpropagation algorithm is introduced to the network in order to correlate the coefficient between the expected and the calculated using a supervised learning [40,41].

Furthermore, the coefficient of the determination (R²) and the root mean square error (RMSE) were used to evaluate the result gotten in the ANN model. The higher the R² with a low RMSE the better the prediction capabilities of the ANN model [42]. The equation is written as equation 5 and 6:

$$R^{2} = 1 - \frac{\sum (x_{i} - y_{i})^{2}}{\sum y_{i}^{2} - \frac{\sum y_{i}^{2}}{n}}$$

$$RMSE = \sqrt{\frac{1}{n} \sum \frac{n}{i=1} (x_{i} - y_{i})^{2}}$$
(6)

$$RMSE = \sqrt{\frac{1}{n} \sum_{i=1}^{n} (x_i - y_i)^2}$$
 (6)

where x_i represent the observed data, y_i is the predicted data and n is the number of observation. The network structure of MLP-FF-ANN is shown in Figure 2.

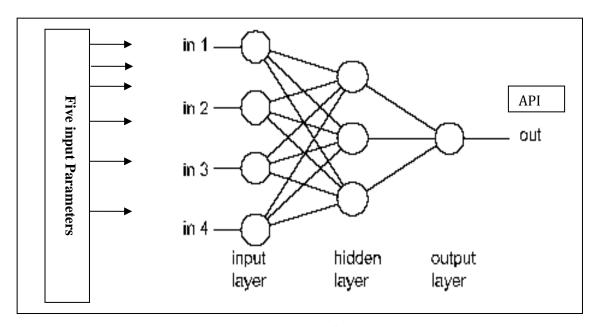


Figure 2. Network structure of MLP-FF-ANN model

Results and Discussion

Spatial Classification of Air Monitoring Stations

The five air quality monitoring sites were spatially classified based on their level of differences and similarities in the activities within the study area. Stations with high level of similarities were unsupervisely grouped into one cluster. This resulted in the formation of two independent clusters in a dendrogram in Figure 3. Station 1, 2, 4 and 5 were successfully integrated into cluster 1, while station 3 stands independent from others as cluster 2.

Cluster 1 is classified as moderate polluted area (MPA) that is strongly associated with the nature of activities from both point source and non-point source. These areas are characterized with commercial and industrial practices, heavy traffic congestion, large scale forest fire from Sumatra (Indonesia) and airports [43,44]. Part of this area is the extensively Rajan River in Borneo (Sarawak) with agricultural activities and a well-developed water transport system [43]. This four stations exhibit a strong similarities in their characteristics.

Cluster 2 is classified as a residential area, tourist centre with little industrial activities [43,44]. This cluster can be recognized as a less polluted area (LPA).

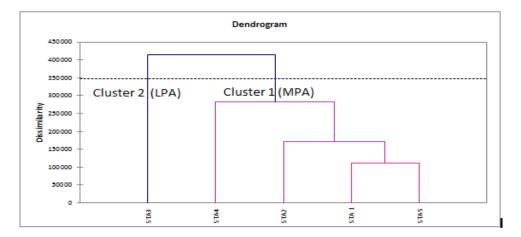


Figure 3. Spatial classification of the air monitoring sites

Discriminate Analysis (DA)

The most significant parameters that best discriminate spatially based on the clusters developed by HACA were determined using standard mode, forward stepwise and backward stepwise DA. The two clusters were used as dependent variables while the five monitored parameters were applied as the independent variables.

The result of the confusion matrix for standard, forward and backward stepwise mode gave a correct assignation of over 87% indicating that only three parameters (PM_{10} , SO_2 and NO_2) discriminate best with a p-value <0.0001. The spatial classification matrix for DA is shown in Table 2.

Identification of The Major Possible Sources of Pollution

The spatial composition pattern of the examined parameters and sources of pollutants were identified using PCA. For each cluster, two PCs were obtained with an eigenvalue greater than one. The cumulative variance gave a correct assignation of more than 58% and 60% of the total variance in the data sets. In order to identify the most significant parameters only factor loading greater than 0.7 were considered for interpretation. Table 3 and Figure 4 show the highlights of selected factors with strong positive loadings (>0.7), eigenvalues greater than one (>1) and cumulative variance. The scree plot diagram for PCA loadings in Figure 5 indicates the cut-off point where strong factors are selected for interpretation.

Table 2. Spatial classification matrix of DA based on clusters

Sampling Stations	Regio	% Correct		
_	Cluster 1	Cluster 2		
Standard mode				
Cluster 1	4158	226	94.84%	
Cluster 2	448	648	59.12%	
Total	4606	874	87.70%	
Forward stepwise mode				
Cluster 1	4158	226	94.84%	
Cluster 2	450	646	58.94%	
Total	4608	872	87.66%	
Backward stepwise				
Mode				
Cluster 1	4158	226	94.84%	
Cluster 2	450	646	58.94%	
Total	4608	872	87.66%	

Cluster 1

The first varifactor (VF1) explains 38.4% of the total variance with a strong positive loading for PM_{10} (0.734) and NO_2 (0.862). Heavy industrial activities, emission from automobiles and aircrafts, Sumatra bush burning, construction sites are the major sources of PM_{10} and NO_2 . Johor and Kemaman houses large industrial and commercial activities [45]. Johor borders the Indonesia were most of the Sumatra bush burning come from. This areas also experiences heavy traffic round the clock.

Table 3. Factor loading after varimax rotation based on clusters

	Cluster 1		Cluster 2	
Variables	VF1	VF2	VF1	VF2
СО	0.423	0.115	0.608	-0.173
O_3	-0.008	0.992	0.093	0.906
PM_{10}	0.734	0.035	0.806	0.205
SO_2	0.679	-0.047	0.622	-0.374
NO_2	0.862	-0.018	0.741	0.18
Eigenvalue	1.922	1.001	1.966	1.062
Variability (%)	38.44	20.029	39.321	21.247
Cumulative %	38.44	58.469	39.321	60.567

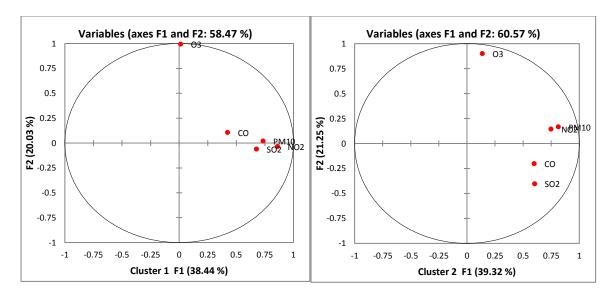


Figure 4. Factor loading plot after varimax rotation for cluster 1 and 2

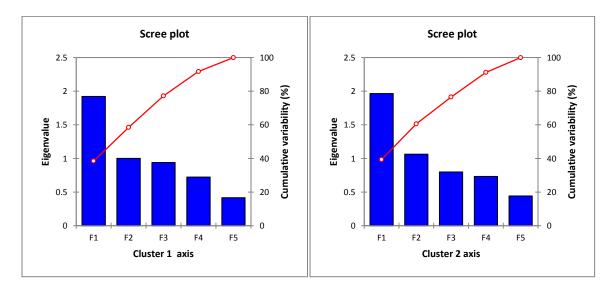


Figure 5. Scree plot diagram for PCA loading in cluster 1 and 2

 O_3 (0.992) is the most significant parameter with a strong positive loadings in the second varifactor in cluster 1. It accounts for over 20% of the total variance in the data set. Its formation is produced by photochemical oxidation and act as the main component of photochemical smog [46]. The concentration of O_3 is largely dependent on the availability of its precursors (NOx, CO and VOCs), since O_3 is a secondary pollutant. These precursors are from industrial activities and vehicular emission [44,47].

Cluster 2

The second cluster exhibit a strong positive loading for PM_{10} (0.806) and NO_2 (0.741) that explains over 39% in the data set. Heavy construction activities and emissions from automobiles contribute immensely to PM_{10} emission. [48,49]. PM_{10} are mostly emitted from heavy construction work for city development as well as resuspension of soil and road dust. Large proportion of NO_2 is produced when nitrogen in fuel is burnt and when at a very high

temperature nitrogen in the air reacts with oxygen [50]. An estimate by [45] show that about 69% of NO_2 is emitted from power stations and industrial activities, 28% from motor vehicles and the remaining 3% makes up other sources.

The second varifactor have a strong positive loading for O_3 (0.906) which accounts for more than 21% of the total variance in the data set. Its concentration is dependent on its precursors (NOx, CO and VOCs) from industrial and motor vehicle emission [47].

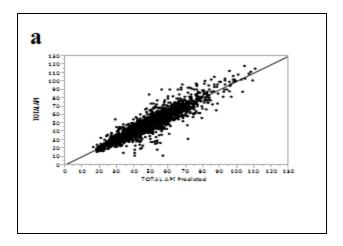
Prediction of Air Pollution Index using ANN

Based on the coefficient of determination (R^2) and root mean square error (RMSE) ANN was used to predict the level of air pollution index. The network structure for the ANN model was run ten times in order to train the network and to approximate any non-linear function with a high level of precision. However, the optimum gauge for the ANN network where the best prediction is achieved was gotten at node six. Further optimization of the network resulted in a decrease in the prediction capability of the MLP-FF-ANN. For training, the highest $R^2 = 0.8493$ and the lowest RMSE = 5.9184 was gotten at node six. The network was also validated at $R^2 = 0.8456$ and RMSE = 6.1128.

Table 4 below show the prediction performance of the MLP-FF-ANN at different nodes based on R² and RMSE. Figure 6 indicate the scatter plot for the training and validation phase of the MLP-FF-ANN. ANN is a sophisticated software capable of predicting the concentration of pollutants as well as give an estimate in the level of air pollution index [38]. It has the ability to learn complex pattern and can synthesise them better than conventional machines [37].

Table 3. MLP-FF-ANN Performance Based on R² and RMSE

Model		Training		Validation	
MLP-FF-ANN	Hidden nodes	\mathbb{R}^2	RMSE	\mathbb{R}^2	RMSE
	[5,1,1]	0.8016	6.7909	0.7977	6.9970
	[5,2,1]	0.8339	6.2122	0.8337	6.3440
	[5,3,1]	0.8432	6.0308	0.8437	6.1501
	[5,4,1]	0.8435	6.0308	0.8415	6.1935
	[5,5,1]	0.8464	5.9755	0.8428	6.1684
	[5,6,1]	0.8493	5.9184	0.8456	6.1128
	[5,7,1]	0.8420	6.0594	0.8380	6.2621
	[5,8,1]	0.8447	6.0080	0.8422	6.1795
	[5,9,1]	0.8452	5.9973	0.8338	6.2466
	[5,10,1]	0.8443	6.0148	0.8423	6.1772



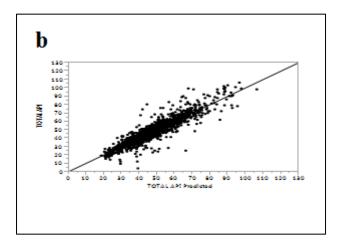


Figure 6. Scatter plots for (a) training and (b) validation phase for MLP-FF-ANN

Conclusion

The spatial variation in the characteristics of air pollution in Malaysia was assessed using multivariate techniques. The five air quality monitoring stations were spatially grouped into two independent clusters using HACA. This classification indicates strong similarities in the characteristics of monitoring sites in the same clusters. HACA helps to minimize the number of monitoring sites that will directly or indirectly reduce the cost and time of monitoring redundant stations. The result for DA in the entire data sets based on clusters developed by HACA gave a correct assignation of more than 87% with P <0.0001 for only three parameters (PM $_{10}$, SO $_{2}$ and NO $_{2}$). This clearly indicates that the three primary and secondary pollutants discriminate best out of the five monitored parameters.

PCA explains 58% and 60% of the total variance in the data sets. The source of air pollution based on PCA loadings after varimax rotation attributes it to heavy industrial activities, emission from automobiles, construction sites and Sumatra bush burning (anthropogenic induced emission). MLP-FF-ANN was used to predict the level of air pollution index with a very high precision. The result for training gave an $R^2 = 0.8493$ and RMSE = 5.9184, while the network was validated at $R^2 = 0.8456$ and RMSE = 6.1128 at node six.

Acknowledgement

The author wish to extend his profound gratitude to the Department of Environment Malaysia for providing the data used for this study. East Coast Environmental Research Institute (ESERI), Universiti Sultan Zainal Abidin, Malaysia is highly appreciated for the wonderful assistance it provided in putting this work to reality.

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